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The Effect of Surface Energy on Temperature Rise Around a Fast Running Crack

by

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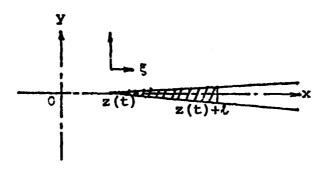
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1. Introduction

Using a local balance law developed by Gurtin [5] for the cohesive zone, we give a system of equations governing the temperature rise around a fast running crack. We note that the effect of surface temperature cannot be neglected for a fast running crack, and we discuss the equations under simplifying assumptions. In particular, assuming that the surface temperature is much higher than the surrounding temperature, we arrive at a simple solution in closed form. This solution agrees with experimental results of Fuller, Fox, and Field [2] for polymethyl methacrylate showing that the temperature rise at the crack tip is independent of crack speed.

2. Theory

Consideration will be restricted to a semi-infinite crack in an infinite plate stressed symmetrically with respect to the plane of the crack.



We assume that the crack is moving with constant velocity v in the direction of negative x.

(See the Figure.)

Neglecting thermo-mechanical coupling we have the following energy balance law governing the temperature rise $\theta = \theta(x,y,t)$ away from the crack:

$$\rho c \frac{\partial \theta}{\partial t} = k \left(\frac{\partial^2 \theta}{\partial x^2} + \frac{\partial^2 \theta}{\partial y^2} \right)$$
 (2.1)

where ρ is the density, k conductivity and c specific heat. Let z(t) label the end of cohesive zone and ℓ its length, so that $z(t) + \ell$ gives the position of the crack tip.

Since the work rate f(x,t) due to plastic work in the cohesive zone will be symmetric about the plane of the crack, there will be no heat conduction across the line $\{y = 0, x < z(t)\}$; hence

$$k \frac{\partial \theta}{\partial y} = 0, \quad y = 0, \quad x < z(t).$$
 (2.2)

We allow the crack surface to have (surface) temperature rise $z(x,t) (\geq 0)$, continuous in x(>z(t)).

According to a recent theory of Gurtin [5], the local balance law in the cohesive region is given in the form

$$\dot{\epsilon}_{f} = h + g \cdot \dot{\delta}, \qquad (2.3)$$

where h is the heat flow per unit surface into the crack surface from the body (cf., e.g., (5.6) in [5]).

Using (2.3) we have (by routine assumptions and derivations)

$$\frac{\beta}{2} \dot{\phi}(x,t) = h + \frac{f(x,t)}{2}, \quad y = 0, \quad x > z(t),$$

$$k \frac{\partial \theta}{\partial y} = h, \qquad y = 0^{\pm}, \quad x > z(t),$$
(2.4)

where β is a constant. We assume that h has the form $h = \alpha(\theta - \phi), \qquad (2.5)$

where α (= constant) is the surface conductivity. We note that, in (2.4)₁ f(x,t) = 0 at x > z(t) + ℓ , and we neglect heat loss into the surrounding air. In Gurtin [5], the energy of the newly formed free surfaces is assumed to be constant when these surfaces are exposed to a constant environmental temperature. For a <u>fast</u> running crack, however, this assumption is redundant.

Assuming steady-state conditions and introducing the moving coordinate $\xi = x - z(t)$, the equations (2.1)-(2.5) become

¹See Döll [4].

$$\rho cv \frac{\partial \theta}{\partial \xi} = k \left(\frac{\partial^2 \theta}{\partial \xi^2} + \frac{\partial^2 \theta}{\partial y^2} \right), \quad y > 0, \quad -\infty < \xi < \infty,$$

$$k \frac{\partial \theta}{\partial y} = 0, \qquad y = 0, \quad \xi < 0,$$

$$\frac{\theta}{2} v \frac{\partial \phi}{\partial \xi} = \alpha (\theta - \phi) + \frac{\alpha(\xi)}{2}, \quad y = 0, \quad \xi > 0,$$

$$k \frac{\partial \theta}{\partial y} = \alpha (\theta - \phi), \qquad y = 0^{\pm}, \quad \xi > 0,$$

$$(2.6)$$

where $g(\xi) := f(\xi + z(t),t)$ is the work rate in the cohesive region. By $(2.6)_{3,4}$, we have

$$b \frac{\partial \omega}{\partial \xi} = \frac{\partial \theta}{\partial y} + \frac{q(\xi)}{2k}, \qquad (2.7)$$

where $b = \frac{\beta v}{2k}$. We note β is the heat required to raise the temperature of a unit surface by one degree $(cal/cm^2)^OC$. We expect β to be negligible small. The dimensionless constant b, however, is approximately

 $6.1 \times 10^4 \times \beta$ - 2024 Aluminium Alloy

 $1.7 \times 10^5 \times \beta$ - Mild Steel

1.4×10⁶×β - 6Al-4V Titanium Alloy

 $5.0 \times 10^8 \times \beta$ - Polymethyl Methacrylate (k=5×10⁻⁵/cm/°C/s)

for v = 500 m/sec. Thus, even for β as small as $10^{-5} \sim 10^{-8} \text{cal/cm}^2/^{\circ}$ C, we may not neglect the term $b \frac{\partial w}{\partial y}$ compared to $\frac{\partial \theta}{\partial y}$ in (2.7) if the crack velocity is as large as 500 m/s.

We will discuss the temperature rise around a fast running crack using the above equations, but under certain simplifying assumptions.

3. Analysis and Discussions

Here we assume that $\theta << \omega$ on the crack surface. (Experiments on polymethyl methacrylate show the temperature rise on the crack faces ($\approx 1 \mu m$ in depth) to be about 500 K throughout the velocity range 200~650 m/s [2], in contrast, the maximum temperature rise at a distance of about 0.2~1mm from the crack path, is only 0.1~1 K [3].)

Under this assumption the equations (2.7) become

$$\rho cv \frac{\partial \theta}{\partial \xi} = k(\frac{\partial^2 \theta}{\partial \xi^2} + \frac{\partial^2 \theta}{\partial y^2}), \quad y > 0, \quad -\infty < \xi < \infty,$$

$$k \frac{\partial \theta}{\partial y} = 0, \qquad y = 0, \quad \xi < 0$$

$$\frac{\beta}{2} v \frac{\partial \omega}{\partial \xi} = -\alpha \omega + \frac{q(\xi)}{2}, \qquad y = 0, \quad \xi > 0,$$

$$k \frac{\partial \theta}{\partial y} = -\alpha \omega, \qquad y = 0^{\pm}, \quad \xi > 0.$$

We assume that θ and ϕ tend to zero at infinity. We then have solutions in the form

$$\varphi(\xi) = \begin{cases} \int_{0}^{\ell} \frac{g(t)}{\beta v} e^{-\frac{2\alpha}{\beta v}(\xi - t)} dt & \ell \leq \xi, \\ \int_{0}^{\xi} \frac{g(t)}{\beta v} e^{-\frac{2\alpha}{\beta v}(\xi - t)} dt & 0 \leq \xi < \ell, \\ 0 & \xi < 0, \end{cases}$$

$$\theta(\xi,y) = \int_{0}^{\infty} \frac{\alpha_{\theta}(t)}{k} K(\xi-t,y) dt,$$

where

$$K(x,y) = \frac{1}{\pi} e^{ax} K_0(a \sqrt{x^2+y^2}), \quad a = \frac{\rho cv}{2k},$$

with K the modified Bessel function of the second kind.

Using the Dugdale model, the work rate due to plastic work is given in the form

$$g(x) = \sigma_0 \frac{d\delta(x)}{dx} v,$$

where $\sigma_{_{f O}}$ is the yield stress and δ the separation distance.

Thus the temperature rise $\varphi(\xi)$ for $\xi \geq \ell$ becomes

$$\varphi(\xi) = \left(e^{-\frac{2\alpha l}{v\beta}} \int_{0}^{l} \frac{\sigma_{o} \frac{d\delta(t)}{dt}}{\beta} e^{\frac{2\alpha}{v\beta}t} dt\right) e^{-\frac{2\alpha}{v\beta}(\xi-l)}$$

$$= \left(e^{-\frac{2\alpha l}{v\beta}} \int_{0}^{1} \frac{\sigma_{o} \frac{d\delta(lx)}{dx}}{\beta} e^{\frac{2\alpha l}{v\beta}x} dx\right) e^{-\frac{2\alpha}{v\beta}(\xi-l)}$$
(3.1)

and thus, if $2\alpha l/v\beta$ is negligibly small, (3.1) is approximately,

$$\varphi(\xi) \approx \frac{\sigma_0 \delta(\ell)}{\beta} e^{-\frac{2\alpha \eta}{\beta V}},$$
 (3.2)

where $\eta = \xi - \lambda$.

This result shows, interestingly, that the temperature rise at the crack tip (n = 0) is proportional to $\sigma_0 \delta(\ell)$ with constant of proportionality is $1/\beta$.

$$g(\xi) = \frac{4(1-v^2)\sigma_0^2 v}{E} \ln(\frac{1+\sqrt{\xi/L}}{1-\sqrt{\xi/L}}), \quad 0 < \xi < L.$$

The work rate g(5) for the Dugdale model in small plane strain is computed by Levy and Rice [1] as

Note that we have assumed plastic work in the cohesive zone is completely converted into heat. (This is generally true of the energy expended in plastically deforming a metal.) For partial conversion g should be scaled down appropriately.

Note that φ depends on v only through a dependence on η/v . For the point x = y = 0, say, occupied by the tip at t = 0, η will be the distance from the tip at time $t = \eta/v$. Thus, by (3.2), the temperature rise at this point should depend only on time; it should be independent of v. This result is in agreement with experimental result of Fuller, Fox, and Field [2], who found that the temperature rise at a fixed point on the axis of the crack was approximately independent of crack velocity. In fact, they note that "the results combined to give a temperature rise of approximately 500 K throughout the velocity range studied $(200 \sim 650 \text{ m/s})$."

For the fixed point x = y = 0, (3.2) gives $\varphi \approx \frac{\sigma_0 \delta(\ell)}{\beta} = \frac{2\alpha}{\beta} t$

and hence ϕ has the form

 $\varphi \approx Ae^{-Bt}$,

where $A = \sigma_0 \delta(\ell)/\beta$ and $B = -2\alpha/\beta$.

The data of [2], when averaged, give

 $\phi = 457 \text{ K}$ at $t = 10 \mu s$

 $\varphi = 361 \text{ K}$ at $t = 20 \mu \text{s}$

 $\phi = 304 \text{ K}$ at t = 35µs.

Using the values at $t = 10\mu s$ and $t = 35\mu s$, we find that

$$A = 5.38 \times 10^{2} K$$
.

$$B = 1.63 \times 10^4 \text{sec}^{-1}$$
.

Here we follow Levy and Rice [1] and assume that $\sigma(L)$ is independent of v. Levy and Rice [1], however, found that this temperature rise is proportional to \sqrt{v} .

This gives $\varphi = 388 \text{ K}$ at $t = 20 \mu \text{s}$ as compared to the value $\varphi = 361 \text{ K}$ of [2]. Further, we find that $\varphi = 538 \text{ K}$ at t = 0; that is, the temperature rise at the crack tip is 538 K. For the values $\ell = 1 \text{ mm}$ (which we feel is an upper bound for ℓ) and v = 200 m/s, we find that the dimensionless constant

$$2\alpha l/v\beta = lB/v$$
,

which we neglected in defining (3.2), has the approximate value of 0.08.

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